

RESEARCH ARTICLE

INTERFACE EFFECTS ON AN INFINITE PLANE CONTAINING TWO CIRCULAR NANO-INHOMOGENEITIES

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ABSTRACT

Based on the surface theory, employing complex variable function method, the problem of an isotropic elastic plane containing two circular nano-inhomogeneities is studied. The solutions of stress field of any point at the nano-inhomogeneities and plane with interface effects are obtained. The surface effects on the stress fields of the whole plane structure are analyzed.

Key words: Nano-inhomogeneities; Complex Variable Function Method, Surface Theory

INTRODUCTION

With the development of science and technology, the study of the mechanical behavior of inhomogeneous materials containing nanosized inclusions or holes has attracted great interest. The existing literatures show that researches with interface/surface effects of an inclusion or a hole on mechanical behavior of inhomogeneous medium have achieved some achievements (Wang, 2007; Ou, 2008; Grekov, 2014; Ou et al., 2009; Tian, 2007; Tian, 2007; Ou, 2015; Mogilevskaya, 2008; Ou, 2015), but the lack of studies of surface/interface effects of multiple holes or inclusions on inhomogeneous media. Gong and Meguid, (1993) use the complex variable function method to analyze the interacting circular inhomogeneities in plane elastostatics without the surface stress. Based on the displacement Gurtin and Murdoch models, Mogilevskaya and Crouch (2008), the boundary integral method are used to analyze the two dimensional problems with multiple nanosized circular holes. The purpose of the paper is to analyze the effects of surface on the infinite plane containing two circular nano-inhomogeneities subjected to stress and shear stress at infinity. Based on the surface theory, complex variable function method is used here to solve the deformation field.

Mathematical Formulations

Consider an isotropic elastic plane M containing two circular nano-inhomogeneities O_1 and O_2 as shown in Fig. 1. It is subjected to stress and shear stress at infinity of the plane. With the complex variable method, the stress and the displacement can be expressed in terms of two analytic functions $\varphi(z)$ and $\psi(z)$ as follows

$$2\mu(u_x + iu_y) = k\varphi(z) - z\overline{\varphi'(z)} - \overline{\psi(z)} \quad (1)$$

$$\sigma_{xx} + \sigma_{yy} = 2(\varphi'(z) + \overline{\varphi'(z)}) \quad (2)$$

$$\sigma_{yy} - \sigma_{xx} + 2i\sigma_{xy} = 2(\bar{z}\varphi''(z) + \psi'(z)) \quad (3)$$

where u_{ij} and σ_{ij} are displacement and stress tensor, respectively; $k = 3 - 4\nu$ for plane strain and $k = (3 - \nu)/(1 + \nu)$ for plane stress; μ and ν are the shear modulus and Poisson's ratio, respectively; $z = x + iy = ae^{i\theta}$. Airy's stress function U can be related to the above two functions by

$$U = \text{Re}(\bar{z}\varphi(z) + \eta(z)), \quad \eta'(z) = \psi(z) \quad (4)$$

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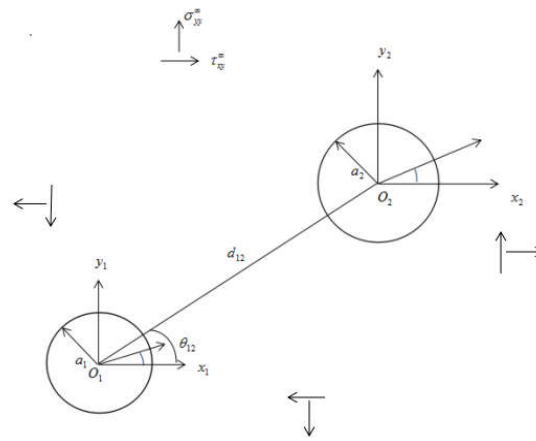


Fig. 1. Elastic plane containing two circular nano-inhomogeneities

The components of stress and displacement in terms of polar coordinates are

$$2\mu(u_r + iu_\theta) = e^{-i\theta} \left(k\varphi(z) - z\overline{\varphi'(z)} - \overline{\psi(z)} \right) \tag{5}$$

$$\sigma_{rr} + \sigma_{\theta\theta} = 2\left(\varphi'(z) + \overline{\varphi'(z)}\right) \tag{6}$$

$$\sigma_{\theta\theta} - \sigma_{rr} + 2i\sigma_{r\theta} = 2\left(\overline{z}\varphi''(z) + \psi'(z)\right)e^{2i\theta} \tag{7}$$

Equations (6) and (7) can be expressed in the following complex variable form

$$\sigma_{rr} - i\sigma_{r\theta} = \varphi'(z) + \overline{\varphi'(z)} - \left(\overline{z}\varphi''(z) + \psi'(z)\right)e^{2i\theta} \tag{8}$$

In the bulk, the constitutive equations are

$$\sigma_{ij}^B = \lambda\varepsilon_{kk}\delta_{ij} + 2\mu\varepsilon_{ij} \tag{9}$$

In the (r, θ, t) coordinate, the Young-Laplace equations are

$$\begin{aligned} \nabla_s \cdot \tau &= \left(\frac{1}{r} \frac{\partial \sigma_{\theta\theta}^s}{\partial \theta} + \frac{\partial \sigma_{tt}^s}{\partial t} \right) e_t \\ &+ \left(\frac{1}{r} \frac{\partial \sigma_{\theta\theta}^s}{\partial \theta} + \frac{\partial \sigma_{t\theta}^s}{\partial t} \right) e_\theta + \left(-\frac{\partial \sigma_{\theta\theta}^s}{r} \right) n \end{aligned} \tag{10}$$

$$\left[\left[\sigma_{rt}^B \right] \right] e_t + \left[\left[\sigma_{r\theta}^B \right] \right] e_\theta + \left[\left[\sigma_{rr}^B \right] \right] n = -\nabla_s \cdot \tau \tag{11}$$

$$\sigma_{\alpha\beta}^s = \tau^0 \delta_{\alpha\beta} + 2(\mu^s - \tau^0) \varepsilon_{\alpha\gamma} \delta_{\gamma\beta} + (\lambda^s + \tau^0) \varepsilon_{\gamma\gamma} \delta_{\alpha\beta} \tag{12}$$

where superscripts B and S are used to denote the quantities corresponding to bulk and interface between matrix and inhomogeneity; λ and μ are the Lamé constants; n is the normal vector on the interface; τ^0 is the residual surface stress under unstrained conditions; δ_{ij} is the Kronecker delta; $\left[\left[* \right] \right] = (*)_M - (*)_I$ denotes the jump across the matrix-inhomogeneity interface; $i, j, k = 1, 2, 3$; $\alpha, \beta, \gamma = 1, 2$.

Assume that the inhomogeneities are perfectly bonded to the matrix. Then the displacements are continuous at the interface

$$(u_r + iu_\theta)_M = (u_r + iu_\theta)_I + (u_r + iu_\theta)_I^* \tag{13}$$

where the last term is the displacement induced by the prescribed uniform dilatational eigenstrain ε^* , i.e., $\varepsilon_{11}^* = \varepsilon_{22}^* = \varepsilon^*$, and

$$(u_r + iu_\theta)_I^* = a_{0,1} \varepsilon^* \quad \text{at} \quad a_1 = a_{0,1} \tag{14}$$

Here, $z_1 = a_1 e^{i\theta_1}$.

From equations (10) and (11), we have

$$\llbracket \sigma_{rt}^B \rrbracket = - \left(\frac{1}{a_{0,1}} \frac{\partial \sigma_{\theta t}^s}{\partial \theta} + \frac{\partial \sigma_{tt}^s}{\partial t} \right) \tag{15}$$

$$\llbracket \sigma_{r\theta}^B \rrbracket = - \left(\frac{1}{a_{0,1}} \frac{\partial \sigma_{\theta\theta}^s}{\partial \theta} + \frac{\partial \sigma_{\theta t}^s}{\partial t} \right) \tag{16}$$

$$\llbracket \sigma_{rr}^B \rrbracket = \frac{\sigma_{\theta\theta}^s}{a_{0,1}} \tag{17}$$

For plane problems, the quantities with respect to t are 0. Thus equation (15) is automatically satisfied. Equations (16) and (17) can be expressed

$$\llbracket \sigma_{rr}^B - i\sigma_{r\theta}^B \rrbracket = \frac{\sigma_{\theta\theta}^s}{a_{0,1}} + \frac{i}{a_{0,1}} \frac{\partial \sigma_{\theta\theta}^s}{\partial \theta} \tag{18}$$

The left-hand side of equation (18) can be written in terms of potential functions by using equation (8). For the right-hand side, the surface stress $\sigma_{\theta\theta}^s$ by using equation (12) can be written as

$$\sigma_{\theta\theta}^s = \tau^0 + 2(\mu^s - \tau^0) \varepsilon_{\theta\theta} + (\lambda^s + \tau^0) (\varepsilon_{tt} + \varepsilon_{\theta\theta}) \tag{19}$$

When $a_1 = a_{0,1}$, the elastic strain by using equations (6), (7) and (9) can be obtained from the following equations

$$\varepsilon_{rr} + \varepsilon_{\theta\theta} = \frac{1}{\Gamma} (\varphi'(z) + \overline{\varphi'(z)}) \tag{20}$$

$$\varepsilon_{\theta\theta} - \varepsilon_{rr} + 2i\varepsilon_{r\theta} = \frac{1}{\mu} (\bar{z}\varphi''(z) + \psi'(z)) e^{2i\theta} \tag{21}$$

Here, $\Gamma = \mu + \lambda$. Therefore

$$\begin{aligned} \varepsilon_{\theta\theta} &= \frac{1}{2\Gamma} (\varphi'(z) + \overline{\varphi'(z)}) + \frac{1}{4\mu} (\bar{z}\varphi''(z) + \psi'(z)) e^{2i\theta} \\ &+ \frac{1}{4\mu} (\overline{z\varphi''(z)} + \overline{\psi'(z)}) e^{-2i\theta} \end{aligned} \tag{22}$$

The strain $\varepsilon_{\theta\theta}$ is continuous at the interface due to the continuous displacement at the interface. Thus in the following derivation, the strain is calculated from the matrix. Note that $\varepsilon_{tt} = 0$ for plane strain and $\varepsilon_{tt} = \frac{\nu}{\nu-1} (\varepsilon_{rr} + \varepsilon_{\theta\theta})$ with $a_1 = a_{0,1}$ for plane stress.

Because of the discontinuity of ε_{tt} at the interface, the mean strain is used

$$\varepsilon_{tt} = \frac{1}{2}((\varepsilon_{tt})_M + (\varepsilon_{tt})_I) \tag{23}$$

$(\varepsilon_{tt})_M$ can be obtained from equation (20), however, $(\varepsilon_{tt})_I$ is

$$(\varepsilon_{tt})_I = \frac{\nu_I}{\nu_I - 1}((\varepsilon_{rr} + \varepsilon_{\theta\theta})_I^e + 2\varepsilon^*) \tag{24}$$

where $(\varepsilon_{rr} + \varepsilon_{\theta\theta})_I^e$ can be obtained by using equation (20).

Since no singularities are assumed to reside inside or on the boundary of the inhomogeneity, $\varphi(z)$ and $\psi(z)$ can be expanded into Laurent series as follows

$$\varphi_I(z_1) = \sum_{n=1}^{\infty} H_{n,1} z_1^n \tag{25a}$$

$$\psi_I(z_1) = \sum_{n=1}^{\infty} L_{n,1} z_1^n \tag{25b}$$

However, if there are one inhomogeneity in the matrix M (Tianet al., 2007), $\varphi(z)$ and $\psi(z)$ can be expanded into Laurent series as follows

$$\varphi_M(z_1) = Az_1 + \sum_{n=1}^{\infty} F_{n,1} z_1^{-n} \tag{26a}$$

$$\psi_M(z_1) = Bz_1 + \sum_{n=1}^{\infty} B_{n,1} z_1^{-n} \tag{26b}$$

When there are two inhomogeneity in the matrix M , the Airy's stress function can be expanded by [Gong et al.,1993] as follows

$$U = U_0 + \sum_{k=1}^2 U_k \tag{27}$$

where U_0 is the stress function corresponding to the uniform stress state at infinity in the absence of the inhomogeneity and the stress function U_k is contains singularities inside the k-th inhomogeneity. So U_0 can be expanded as

$$U_0 = \text{Re}(\bar{z}_1 \varphi_0(z_1) + \eta_0(z_1)), \quad \eta'_0(z_1) = \psi_0(z_1) \tag{28a}$$

In the view of equations (2), (3), (26) and England (1971), we have

$$\varphi_0(z_1) = \frac{\sigma_{xx}^{\infty} + \sigma_{yy}^{\infty}}{4} z_1 = Az_1 \tag{28b}$$

$$\psi_0(z_1) = \frac{\sigma_{yy}^{\infty} - \sigma_{xx}^{\infty} + 2i\sigma_{xy}^{\infty}}{2} z_1 = Bz_1 \tag{28c}$$

where σ_{yy}^{∞} , σ_{xx}^{∞} and σ_{xy}^{∞} are the far-field stresses which in the case of our study are assumed to be $\sigma_{yy}^{\infty} = \sigma_0$, $\sigma_{xx}^{\infty} = c\sigma_0$, $\sigma_{xy}^{\infty} = 0$,

$$\frac{\sigma_{xx}^{\infty}}{\sigma_{yy}^{\infty}} = c \text{ (real number)} \begin{cases} c = 1 \text{ (biaxial loadings)} \\ c = 0 \text{ (uniaxial loadings)} \\ c = -1 \text{ (shear loadings)} \end{cases}$$

U_k can be expanded as

$$U_k = \text{Re}(\bar{z}_k \hat{\varphi}(z_k) + \hat{\eta}(z_k)), \quad \hat{\eta}'(z_k) = \hat{\psi}(z_k) \tag{29a}$$

$$\hat{\phi}(z_k) = \sum_{n=1}^{\infty} F_{n,k} z_k^{-n} \tag{29b}$$

$$\hat{\psi}(z_k) = \sum_{n=1}^{\infty} B_{n,k} z_k^{-n} \tag{29c}$$

$$z_2 = z_1 - d_{12} e^{i\theta_{12}} \tag{30}$$

Substituting equations (28), (29), (30) into equation (27), it can be reduced to the same form as equation (4),

$$\varphi_M(z_1) = Az_1 + \sum_{n=1}^{\infty} F_{n,1} z_1^{-n} + \sum_{n=1}^{\infty} M_{n,1} z_1^n \tag{31a}$$

$$\psi_M(z_1) = Bz_1 + \sum_{n=1}^{\infty} B_{n,1} z_1^{-n} + \sum_{n=1}^{\infty} K_{n,1} z_1^n \tag{31b}$$

Here,

$$M_{n,1} = \sum_{p=1}^{\infty} C_{n+p-1}^{p-1} F_{p,2} (-1)^p \frac{1}{d_{12}^{n+p}} e^{-(n+p)i\theta_{12}}$$

$$K_{n,1} = \sum_{p=1}^{\infty} C_{n+p-1}^{p-1} B_{p,2} (-1)^p \frac{1}{d_{12}^{n+p}} e^{-(n+p)i\theta_{12}}$$

$$- \sum_{p=1}^{\infty} C_{n+p-1}^{p-1} F_{p,2} (-1)^p \frac{1}{d_{12}^{n+p-1}} e^{-(n+p+1)i\theta_{12}}$$

In the same way, the displacement and stress boundary condition of O_2 can be respectively expressed as

$$(u_r + iu_\theta)_M = (u_r + iu_\theta)_I + a_{0,2} \mathcal{E}^* \tag{32}$$

$$\left[\sigma_{rr}^B - i\sigma_{r\theta}^B \right] = \frac{\sigma_{\theta\theta}^s}{a_{0,2}} + \frac{i}{a_{0,2}} \frac{\partial \sigma_{\theta\theta}^s}{\partial \theta} \tag{33}$$

$\varphi(z)$ and $\psi(z)$ can be expanded into Laurent series as

$$\varphi_I(z_2) = \sum_{n=1}^{\infty} H_{n,2} z_2^n \tag{34a}$$

$$\psi_I(z_2) = \sum_{n=1}^{\infty} L_{n,2} z_2^n \tag{34b}$$

$$\varphi_M(z_2) = Az_2 + \sum_{n=1}^{\infty} F_{n,2} z_2^{-n} + \sum_{n=1}^{\infty} M_{n,2} z_2^n \tag{35a}$$

$$\psi_M(z_2) = Bz_2 + \sum_{n=1}^{\infty} B_{n,2} z_2^{-n} + \sum_{n=1}^{\infty} K_{n,2} z_2^n \tag{35b}$$

Here,

$$M_{n,2} = \sum_{p=1}^{\infty} C_{n+p-1}^{p-1} F_{p,1} (-1)^p \frac{1}{d_{12}^{n+p}} e^{-(n+p)i\theta_{12}}$$

$$K_{n,2} = \sum_{p=1}^{\infty} C_{n+p-1}^{p-1} B_{p,1} (-1)^p \frac{1}{d_{12}^{n+p}} e^{-(n+p)i\theta_{12}}$$

$$- \sum_{p=1}^{\infty} C_{n+p-1}^{p-1} F_{p,1} (-1)^p \frac{1}{d_{12}^{n+p-1}} e^{-(n+p+1)i\theta_{12}}$$

Substituting equations (5), (14), (25), (31) into equation (13), which are the displacement of the inclusion O_1 , it is expressed as follows

$$\frac{K_M}{\mu_M} \left(Az_1 + \sum_{n=1}^{\infty} F_{n,1} z_1^{-n} + \sum_{n=1}^{\infty} M_{n,1} z_1^n \right) - \frac{A}{\mu_M} z_1 - \frac{1}{\mu_M} \sum_{n=1}^{\infty} \bar{M}_{n,1} z_1^{-n+2} a_1^{2n-2} n - \frac{B}{\mu_M} z_1^{-1} a_1^2$$

$$\begin{aligned}
 & -\frac{1}{\mu_M} \sum_{n=1}^{\infty} \bar{B}_{n,1} z_1^n a_1^{-2n} - \frac{1}{\mu_M} \sum_{n=1}^{\infty} \bar{K}_{n,1} z_1^{-n} a_1^{2n} \\
 & + \frac{1}{\mu_M} \sum_{n=1}^{\infty} \bar{F}_{n,1} z_1^{n+2} a_1^{-(2n+2)} n \\
 & = \frac{K_I}{\mu_I} \sum_{n=1}^{\infty} H_{n,1} z_1^n - \frac{1}{\mu_I} \sum_{n=1}^{\infty} \bar{H}_{n,1} z_1^{-n+2} a_1^{2n-2} n \\
 & - \frac{1}{\mu_I} \sum_{n=1}^{\infty} \bar{L}_{n,1} z_1^{-n} a_1^{2n} + \frac{2a_{0,1} \varepsilon^* z_1}{a_1}
 \end{aligned} \tag{36}$$

As to the same the coefficients of z_1^n , we can obtain the following equations

$$\begin{aligned}
 & \frac{K_M}{\mu_M} A + \frac{K_M}{\mu_M} M_{1,1} - \frac{A}{\mu_M} - \frac{1}{\mu_M} \bar{M}_{1,1} - \frac{1}{\mu_M} \bar{B}_{1,1} a_1^{-2} \\
 & = \frac{K_I}{\mu_I} H_{1,1} - \frac{1}{\mu_I} \bar{H}_{1,1} + \frac{2a_{0,1} \varepsilon^*}{a_1} \\
 & \frac{1}{\mu_M} \bar{M}_{2,1} a_1^2 = \frac{1}{\mu_I} \bar{H}_{2,1} a_1^2 \\
 & \frac{K_M}{\mu_M} F_{1,1} - \frac{3}{\mu_M} \bar{M}_{3,1} a_1^4 - \frac{B}{\mu_M} a_1^2 - \frac{1}{2\mu_M} \bar{K}_{1,1} a_1^2 \\
 & = -\frac{3}{\mu_I} \bar{H}_{3,1} a_1^4 - \frac{1}{\mu_I} \bar{L}_{1,1} a_1^2 \\
 & \frac{K_M}{\mu_M} M_{2,1} - \frac{1}{\mu_M} \bar{B}_{2,1} a_1^{-4} = \frac{K_I}{\mu_I} H_{2,1} \\
 & \frac{K_M}{\mu_M} M_{3,1} + \frac{1}{\mu_M} \bar{F}_{1,1} a_1^{-4} - \frac{1}{\mu_M} \bar{B}_{3,1} a_1^{-6} = \frac{K_I}{\mu_I} H_{3,1}
 \end{aligned} \tag{37}$$

Similarly, we can obtain the coefficients of z_2^n by substituting equations (5), (34), (35) into equation (32), which are the displacement of the inclusion O_2 . Due to the stress boundary O_1 and O_2 , the coefficients of z_1^n and z_2^n can be calculated by substituting equations (8), (19), (22), (23), (24), (25), (31) into equation (18), and by substituting equations (8), (19), (22), (23), (24), (34), (35) into equation (33).

The solution yields

$$B_{2,2} = B_{2,1} = H_{2,2} = H_{2,1} = M_{2,2} = M_{2,1} = 0$$

Then the unknown coefficients $F_{1,1}, B_{1,1}, B_{3,1}, H_{1,1}, H_{3,1}, L_{1,1}, F_{1,2}, B_{1,2}, B_{3,2}, H_{1,2}, H_{3,2}, L_{1,2}$ are determined.

In the matrix M , the stresses are

$$\begin{aligned}
 \sigma_{rr} = & 2 \left(A - F_{1,1} a_1^{-2} \cos(2\theta_1) - F_{1,2} \frac{1}{d_{12}} \cos(2\theta_{12}) \right) \\
 & - 2F_{1,1} a_1^{-2} \cos(2\theta_1) - 9F_{3,2} \frac{a_1^2}{d_{12}^3} \cos(5\theta_{12} - 4\theta_1) \\
 & + 3B_{3,1} a_1^{-4} \cos(2\theta_1) + B_{1,2} \frac{1}{d_{12}^2} \cos(2\theta_{12} - 2\theta_1) \\
 & + 9B_{3,2} \frac{a_1^2}{d_{12}^4} \cos(4\theta_{12} - 4\theta_1) + B_{1,1} a_1^{-2} \\
 & - F_{1,2} \frac{1}{d_{12}^2} \cos(3\theta_{12} - 2\theta_1) - B \cos(2\theta_1)
 \end{aligned} \tag{38a}$$

$$\begin{aligned} \sigma_{r\theta} = & 9F_{3,2} \frac{a_1^2}{d_{12}^3} \sin(5\theta_{12} - 4\theta_1) \\ & - 3B_{3,1} a_1^{-4} \sin(2\theta_1) - B_{1,2} \frac{1}{d_{12}^2} \sin(2\theta_{12} - 2\theta_1) \\ & + F_{1,2} \frac{1}{d_{12}^2} \sin(3\theta_{12} - 2\theta_1) + 2F_{1,1} a_1^{-2} \sin(2\theta_1) \\ & - 9B_{3,2} \frac{a_1^2}{d_{12}^4} \sin(4\theta_{12} - 4\theta_1) - B \sin(2\theta_1) \end{aligned} \tag{38b}$$

$$\begin{aligned} \sigma_{\theta\theta} = & 2 \left(A - F_{1,1} a_1^{-2} \cos(2\theta_1) - F_{1,2} \frac{1}{d_{12}} \cos(2\theta_{12}) \right) \\ & + 2F_{1,1} a_1^{-2} \cos(2\theta_1) + 9F_{3,2} \frac{a_1^2}{d_{12}^3} \cos(5\theta_{12} - 4\theta_1) \\ & - 3B_{3,1} a_1^{-4} \cos(2\theta_1) - B_{1,2} \frac{1}{d_{12}^2} \cos(2\theta_{12} - 2\theta_1) \\ & - 9B_{3,2} \frac{a_1^2}{d_{12}^4} \cos(4\theta_{12} - 4\theta_1) - B_{1,1} a_1^{-2} \\ & + F_{1,2} \frac{1}{d_{12}^2} \cos(3\theta_{12} - 2\theta_1) + B \cos(2\theta_1) \end{aligned} \tag{38c}$$

In the inhomogeneity O_1 , the stresses are

$$\sigma_{rr} = 2H_{1,1} - L_{1,1} \cos(2\theta_1) \tag{39a}$$

$$\sigma_{r\theta} = -6a_1^2 H_{3,1} \sin(2\theta_1) - L_{1,1} \sin(2\theta_1) \tag{39b}$$

$$\sigma_{\theta\theta} = 2H_{1,1} + 12a_1^2 H_{3,1} \cos(2\theta_1) + L_{1,1} \cos(2\theta_1) \tag{39c}$$

Numerical Results and Discussions

Based on the above method, the elastic field around the circular inclusions is obtained by numerical simulation. In what follows, we set

$\mu_M = 34.7 \text{ GPa}$, $\nu_M = 0.3$, $\lambda_M = 52 \text{ GPa}$, $\varepsilon^* = 0.3$, $\mu_I = 17.3 \text{ GPa}$, $\lambda_I = 26 \text{ GPa}$, $\nu_I = 0.3$, $\lambda^s = 3.5$, $\mu^s = -6$, $K^s = -8.6$, $\lambda^s = 6.9$, $\mu^s = -0.5$, $K^s = 5.8$, $\tau^0 = 0.1 \text{ N/m}$.

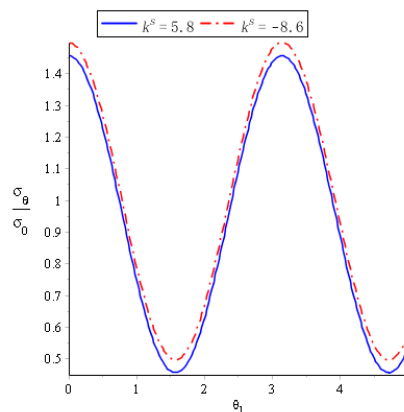


Fig. 2 The variation of normal hoop stress along θ_1
 ($d_{12} = 1000, \theta_{12} = 0$)

Fig. 2 shows the variation of the normal hoop stress along the θ_1 . When the d_{12} tends to infinity and only a circular inclusion effecting on normal stress, there is the same trend of the two curves. Comparing to the Fig. 3 in literature (Tian et al., 2007) [6], it verifies that the result of this paper is the correctness.

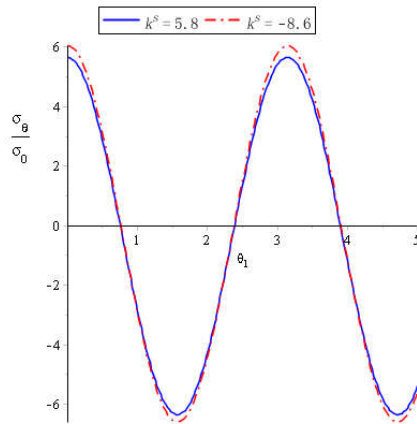


Fig. 3. The variation of normal hoop stress along θ_1
 ($d_{12} = 0.5, \theta_{12} = 0$)

Fig. 3 shows the variation of the normal hoop stress along the θ_1 . Comparing to the Fig. 2, the effect of the inclusion on the normal hoop stress is greater when there are two circular inclusions and the value d_{12} is 0.5.

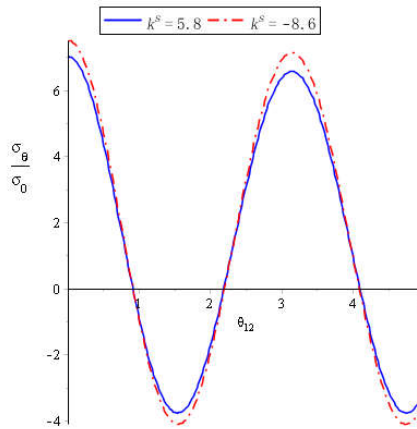


Fig. 4 The variation of normal hoop stress along θ_{12}

Fig. 4 shows the effect of θ_{12} on the normal hoop stress. And the variation of the normal hoop stress along the θ_{12} is similar to those along the θ_1 , but the influence is different

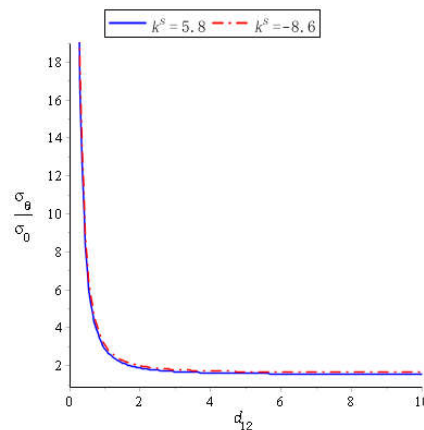


Fig. 5 The variation of normal hoop stress along d_{12}

The influences of the distance d_{12} between the two circular inclusions on the normal hoop stress are shown in Fig. 5. The stress decreases sharply with the increase of d_{12} , and the d_{12} has almost no effect on the normal hoop stress when the values of d_{12} are greater than 2.

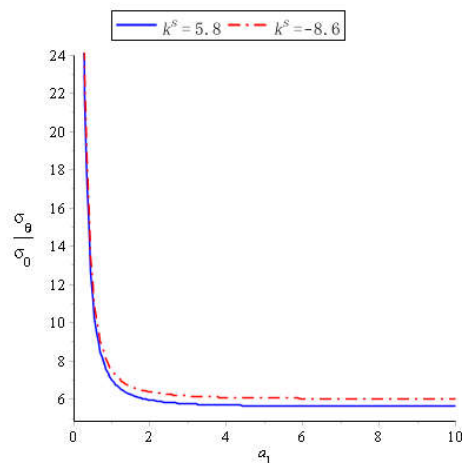


Fig. 6 The variation of normal hoop stress along a_1

Fig. 6 shows the variation of normal hoop stress along the a_1 . From Fig. 6, the influence of the radius a_1 on the normal hoop stress decreases with the increase of a_1 , and it has little effect when it is greater than 2.

Summary and Conclusion

The influence of the interface effect on the stress field of the composites is demonstrated, which can be helpful for the study of other nanocomposites. It is found that the surface elasticity theory illuminates some interesting characteristics of mechanic at the nanoscale.

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